

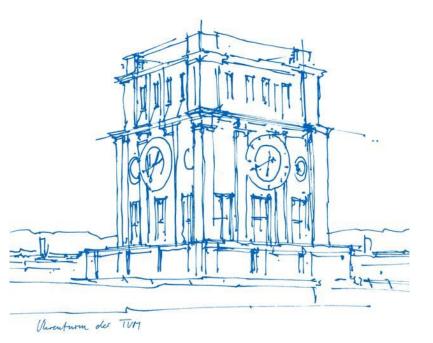
## Parallel Query Processing on GPUs using Sub-operators

Master thesis

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Lehrstuhl für Datenbanken

12. November 2024





#### **Motivation**

- State-of-the-art CPU databases often hit the bandwidth boundary.
- GPUs offer much higher bandwidth.
- GPUs are ubiquitous in consumer and data center environments.
- Al boom suggests that GPUs are here to stay and will be actively developed, can we ride the GPU wave in databases?
- For analytics, why not sacrifice latency for bandwidth?

	CPU	GPU 😻
RAM latency (cycles)	45	470
RAM bandwidth	460 GB/s	3.3 TB/s
ALUs (total)	~400	~15000
Load/Store Units (total)	~300	~3500

GPUs offer higher memory bandwidth and more compute



#### Hardware intuition behind GPUs



Goal: minimize instruction latency



Goal: maximize instruction throughput



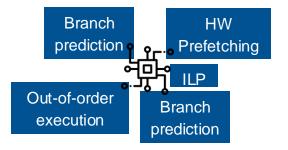




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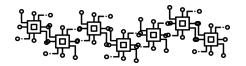


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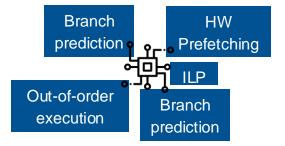




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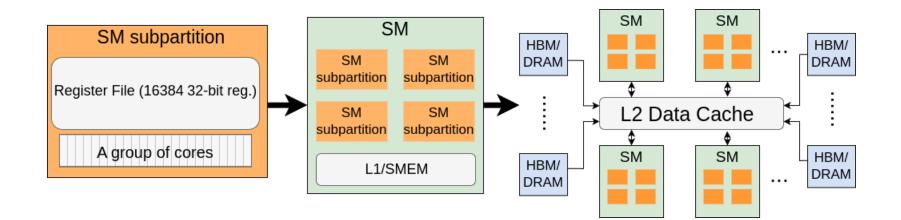




 $\text{Last resort} \qquad \leftarrow \text{Optimization via SMT} \rightarrow \qquad \text{First step} \\$ 

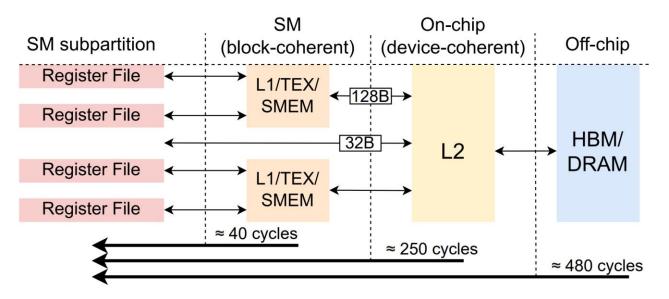


## Quick GPU HW overview





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SMEM – a fast user-managed memory region (same HW unit as L1)



## GPUs in databases

MapD, Omnisci, HeavyDB (mid 2010s):

- LLVM JIT compilation
- Huge code base
- Many physical operators
- Multi-GPU support

TQP (2022):

- Leverage PyTorch
  tensor runtime
- Low effort
- Ok-ish performance

Crystal, Crystal-opt (2022):

- Hand-written SSB queries
- Vectorization
- Fastest SSB runner on GPUs



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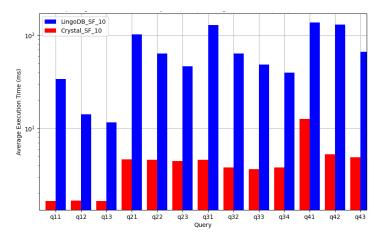
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#### Idea

Approximate Crystal's hand-written performance while preserving HeavyDB's generality by leveraging the existing state-of-the-art query engine.

## Step 1: Gain insights from Crystal – CPU vs. GPU

Good bandwidth utilization means that the query time is proportional to the bandwidth limits of devices. For CPUs and GPUs it is an order of magnitude.

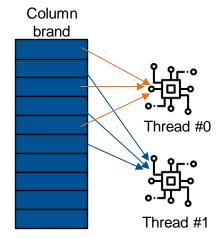




#### Step 1: Crystal - Overview

Fastest GPU runner for simplified (numeric types only) SSB:

- Hand-crafted queries in CUDA C++
- Vectorized execution
  int brand[ITEMS\_PER\_THREAD];
  BlockLoad<..., ITEMS\_PER\_THREAD>(...
  BlockProbeAndPHT\_2<..., ITEMS\_PER\_THREAD>(...
- Collision free hash tables, tricky hash functions
  int hash = (brand[ITEM] \* 7 + (year[ITEM] 1992)) % ((1998-1992+1) \* (5\*5\*40));



Parallelism – vector per thread Vector – 4 elements (in registers)

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Could the GPU's SMT-oriented model be enough to hide latencies like vectorization, even when running "compiled" queries?



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Could the GPU's SMT-oriented model be enough to hide latencies like vectorization, even when running "compiled" queries?

Not really.

Some queries are up to 30% slower.

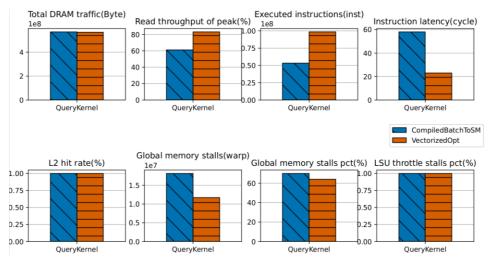




## Step 1: Gain insights from Crystal - Compiled vs. Vectorized

Compiled vs vectorized:

- · Less instructions, but higher instruction latency.
- GPU's SMT is not enough to fully cover latency.
- · Higher selectivity negates vectorization benefit.



SSB Q1.1 Scan+Filter+Sum Reduction. Low selectivity.

## Step 1: Gain insights from Crystal – Register usage

	Vectorized	Compiled
Q11	26	26
Q21 (probe)	28	19
Q21 (build date)	26	19
Q21 (build partkey)	22	16
Q31 (probe)	32	21

Table 4.1: Register usage for selected kernels/"pipelines".

## Register usage – why is it so important?

GPU performance comes from the massive SMT, but how do we achieve it?

There is a limit on simultaneously active threads for a kernel. The limit depends on 3 parameters:

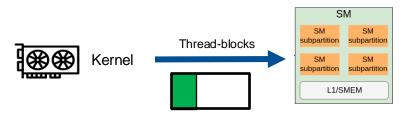
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SMEM usage A thread-block requires N bytes of SMEM, how many N's can SMEM hold at once?

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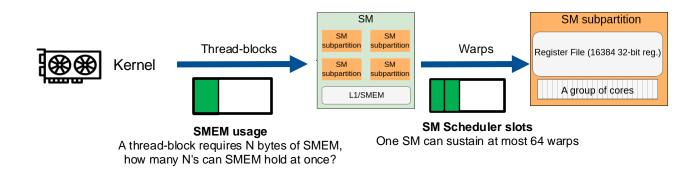
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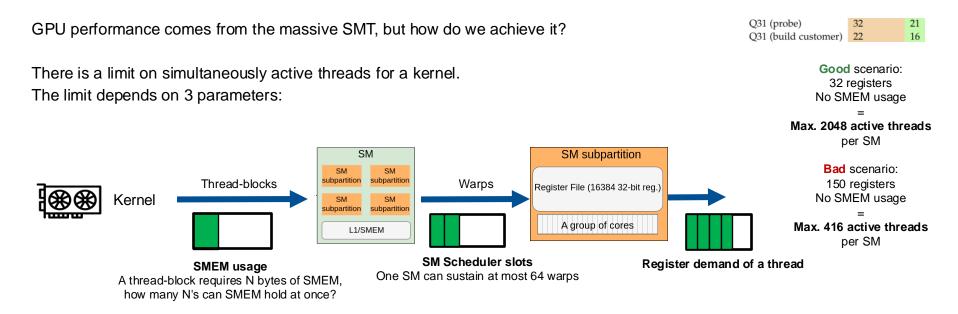


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## Register usage – why is it so important?





## How to map a batch to GPU?

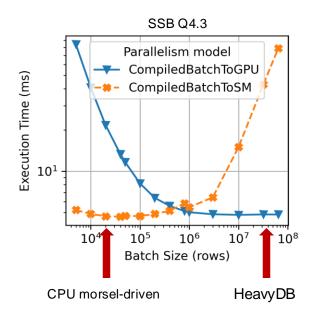
HeavyDB - each batch is processed by the entire GPU.

- Prefers huge batches, default size is 32M rows.
- Low pressure on the bookkeeping infrastructure.

Crystal – each "batch" is processed by a thread-block.

- Prefers small batches (512 rows in the original Crystal).
- A column is linearly stored in memory, threads "slice" into it.

Approach	Thread Blocks : Batches	Intra-batch iteration range	
HeavyDB	1 : <b>N</b>	[0, #Total_threads)	Too large batches
Crystal	1:1	[0, # <b>TB</b> _threads)	Too small batches





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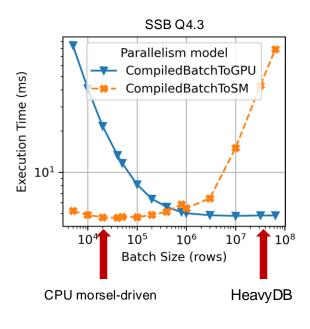
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Mix	1 : <b>N</b>	[0, # <b>TB</b> _threads)	



# Step 2: More general query processing

Crystal has some simplifications:

- Known cardinalities
- Query-specific collision-free hash functions
- Primitive types for reductions

Almost an unrealistic scenario in databases

+ Technical limitations of GPUs (e.g., a thread stack variable is inaccessible to other threads, except for shuffles which are up to 8B)

To achieve a more general query processing, we need:

- General dynamic data structures
- Suitable results representation for generic merge logic



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Device heap

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#### Step 2: More general queries – Kernel local

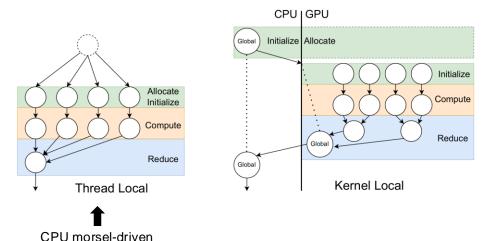
We must be able to easily access composite thread-local results.

Kernel Local – let each kernel have a <u>global</u> memory allocation big enough to fit results at some locality level.

A different address space (not the same as thread's stack) makes the results accessible by a pointer from any thread.

Locality levels that reflect GPU hierarchy:

- 1. Thread
- 2. Warp (max. 32 Threads)
- 3. Thread Block (max. 32 Warps)





malloc() is regarded as a bad practice for GPUs.

- High latency
- Easily congested



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How others deal with dynamic states? HeavyDB: *HyperLogLog, Prefix sum* TQP: *Prefix sum* 

HyperLogLog:

- 1. One pass to estimate cardinality
- 2. Allocate
- 3. Second pass to fill allocation

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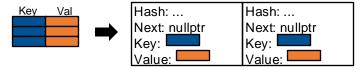
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Workload: filter columns and fill a dynamic vector of entries





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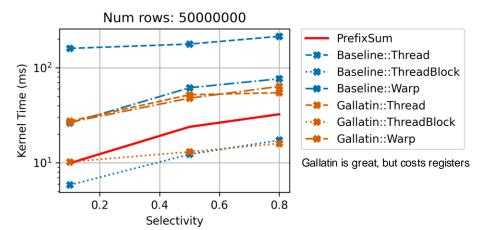
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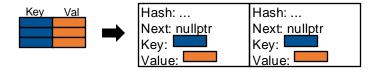
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HyperLogLog:

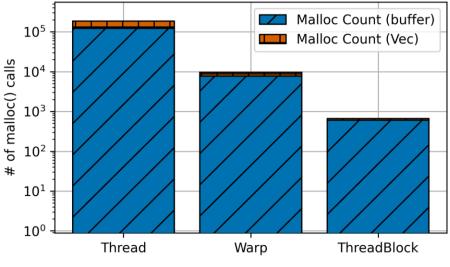
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Workload: filter columns and fill a dynamic vector of entries







Going down by one level leads to an order of magnitude more allocations



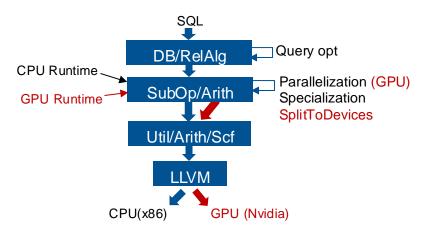
## LingoDB (GPU extension)

- Prototype: replicate LingoDB's Q4.1 code in CUDA C++.
- Main problem: random global memory access during probing.

LingoDB is a CPU state-of-the-art compiled analytical database that uses MLIR.

Soluti-level IR – can pick suitable abstraction layer for modifications.

	Build	Probe-Aggregate
Crystal-opt	~1ms	~7ms
Prototype	~2ms	~20ms

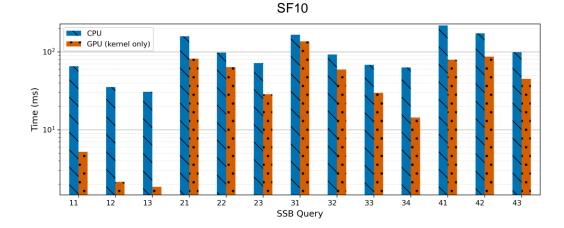




## LingoDB (GPU extension) - Results

Simple queries (Q1.X) are straightforward to implement, but:

- High register usage: 72 vs. 26 in Crystal
- More logic: e.g., nullables

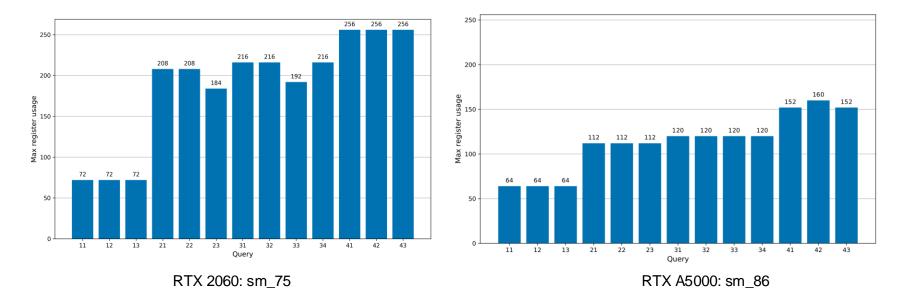


Complex queries have high register pressure:

- LingoDB likes to use i64 where i32 suffices.
- Runtime functions can have big stack and are not inlined (ABI calls cost registers).



#### LingoDB (GPU extension) - Hurdles



Higher register pressure = less threads active at once = less ability to hide latency = slower execution.

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## Conclusion

- Vectorization on GPU is faster when you have room for it.
- Even simple queries, produced by a real-world database engine can incur register pressure on GPUs.
- CPU and GPU can agree on the batch size without perf drawbacks on either side.
- Heap-based dynamic structures enable 2x performance benefit.
- Codegen infrastructure can be shared between two devices, no need for a whole new engine.



#### Future work

- There are multiple heap allocators for GPUs, evaluate them for database workloads. Do we need our own? We would like to have:
  - 1. low-register-cost coarse grained allocations
  - 2. fast free()
  - 3. latency is not so crucial as long as parallelism absorbs it.
- Is i64 needed in all of its uses? Can we inline runtime bitcode? Split complex pipelines?
- How to abort on heap overflow?
- How good chaining really is for HTs on GPUs? Compare LingoDB's chained hash table against HeavyDB's open addressing.

%5 = llvm.mlir.constant(10248 : index) : i64 %6 = llvm.mlir.constant(0 : index) : i64

%21 = nvvm.read.ptx.sreg.tid.x : i32 %22 = llvm.sext %21 : i32 to i64

%32 = nvvm.read.ptx.sreg.ntid.x : i32 %33 = llvm.sext %32 : i32 to i64

%34 = nvvm.read.ptx.sreg.nctaid.x : i32 %35 = llvm.sext %34 : i32 to i64

Index as i64: we have just wasted 5 registers

%116 = arith.extsi %55 : i32 to i128 i128 could be used more conservatively